

# 風水 RAFS Robot Aided FengShui

In an effort to improve the RAFS project, we've developed the following questionnaire. Please take a moment to respond to these questions and help us determine what we did right and wrong.

Rank the following RAFS modules, commenting on any suggestions you have for improvement.					
1. Wandering Module	Impressive <input type="radio"/>	Good <input type="radio"/>	Average <input type="radio"/>	Mediocre <input type="radio"/>	Poor <input type="radio"/>
<p>This module enables the robot to randomly wander around EB 2029 while the chair recognition module executes in the background. When a chair is found, movement halts and the chair recognition takes control.</p> <p>Please comment on this module's implementation, suggesting any improvements that you might recommend.</p>					
2. Chair Recognition Module	Impressive <input type="radio"/>	Good <input type="radio"/>	Average <input type="radio"/>	Mediocre <input type="radio"/>	Poor <input type="radio"/>
<p>This module uses image processing techniques to permit the robot to locate a chair by recognizing a unique color associated with it, adjusting the robot's heading as needed to approach the chair.</p> <p>Please comment on this module's implementation, suggesting any improvements that you might recommend.</p>					
3. Chair Gripping Module	Impressive <input type="radio"/>	Good <input type="radio"/>	Average <input type="radio"/>	Mediocre <input type="radio"/>	Poor <input type="radio"/>
<p>This module enables the robot to reorient itself in order to be able to approach a chair from an angle from which it can get a sturdy grip on the chair, in preparation for transporting the chair to its desired destination.</p> <p>Please comment on this module's implementation, suggesting any improvements that you might recommend.</p>					

