

In an effort to improve the RAFS project, we've developed the following questionnaire. Please take a moment to respond to these questions and help us determine what we did right and wrong.

Rank the following RAFS modules, commenting on any suggestions you have for improvement.								
1. Wandering Module	Impressive	Good	Average	Mediocre	Poor			
		O						
This module enables the robot to randomly wander around EB 2029 while the chair recognition module executes in the background. When a chair is found, movement halts and the chair recognition takes control.								
Please comment on this module's implementation, suggesting any improvements that you might recommend.								
2. Chair Recognition Module	Impressive	Good	Average	Mediocre	Poor			
This module uses image processing techniques to permit the robot to locate a chair by recognizing a unique color associated with it, adjusting the robot's heading as needed to approach the chair.  Please comment on this module's implementation, suggesting any improvements that you might recommend.								
3. Chair Gripping Module	Impressive	Good	Average	Mediocre	Poor			
This module enables the robot to reorient itself it can get a sturdy grip on the chair, in preparation Please comment on this module's implementation	on for transpo	orting the cha	ir to its desire	ed destination	١.			

4. Chair Placement Module	Impressive	Good	Average	Mediocre	Poor
This module uses the robot's laser capabilitie and its gripped chair, as well as to the sides of Please comment on this module's implementa	f the robot. It the	hen places a	chair at a pre	edefined empty de	sk.
Which aspects of the RAFS project part	icularly impre	essed you'	? Please e	xplain.	
Which aspects of the RAFS project explain.	did you fee	el needed s	significant i	mprovement?	Plea

Thanks for your assistance!